

Off-line Critical Conduction Mode PFC LED Driver Evaluation Board User's Manual



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EVAL BOARD USER'S MANUAL

Description	Value	Unit
Input Voltage Range	90 – 305	V rms
Line Frequency Range	45 – 66	Hz
Output Current	700	mA
Output Voltage Range	10 – 41	V dc
Maximum Output Power	25	W
Power Factor (Typical)	0.99	–
THDi (Typical)	< 10	%
Efficiency (Typical)	87.5	%

Introduction

The NCL30060 is intended to control a high performance critical conduction mode (CrM) LED driver providing high power factor and low total harmonic distortion of input current utilizing constant on-time control. This evaluation board provides constant current (CC) to the load over a wide LED string voltage range.

The NCL30060 provides many features including high voltage start-up, direct drive for external power MOSFET, frequency dithering to reduce the EMI profile, maximum on-time protection, over voltage protection, and short circuit protection. These features work together to provide a robust LED driver solution packaged in a compact SO-7 case with one pin removed for improved creepage distance.

As configured, this evaluation board provides 700 mA constant current at up to 25 W and directly interfaces to a string of LEDs. This evaluation board supports 1–10 V and PWM dimming control signals referenced to low voltage secondary circuits. The default configuration supports standard 1–10 V dimming. The evaluation board will support PWM dimming by populating alternate component positions provided on the PCB.

An in-depth description of constant on-time control and performance of a single stage flyback LED driver can be found in the datasheet of a related controller, the [NCL30000](#).

This manual also addresses modifications to change the output current and output voltage ranges. The NCL30060 specification contains additional information on operation of the controller. Design calculations are presented in an Excel® Worksheet available at onsemi.com to aide in customized design applications.

The compact evaluation board is constructed with through-hole components on the top and surface mount components on the bottom side. This driver was designed to meet safety agency requirements but has not been evaluated for compliance. When operating this board, observe safe standard working practices. **High voltages are present and caution should be exercised when handling or probing various points to avoid personal injury or damage to the unit.**

Figures 1 and 2 illustrate the top and bottom sides of the evaluation board. AC input power connects to the block labeled J1. Terminals are marked “L” and “N” representing Line and Neutral leads. The LED load connects to the terminal block labeled J2 with polarity as marked. The anode of the LED load should be connected to “+” and the cathode to “–” terminal. **Never** connect LEDs to the driver while it is running or before the output capacitors discharge after removing input power. With no load connected, the output capacitors charge to > 44 V. Energy stored in the output capacitance can damage or shorten the effective life of the LEDs if improperly discharged into the LEDs.

The schematic for the power section is shown in Figure 3, and dimming schematic is shown in Figure 4.

Dimming control is accessible through the smaller connector labeled J31. Components have already been placed on the board to support standard 1–10 V dimming where a 10 V level provides full output current and 1 V or below reduces the LED current to a minimum level. The response between 1 and 10 V is linear in terms of LED current.

This evaluation board will also support PWM dimming control by populating the board with the appropriate components as listed on the evaluation board Bill of Materials. The board was not intended to support both dimming methods simultaneously; therefore only components for one type of interface should be fitted at a time.

The dimming interfaces are optional and do not require any connections if dimming is not required. This evaluation board does not support phase-cut or TRIAC dimming functions.

NCL30060GEVB

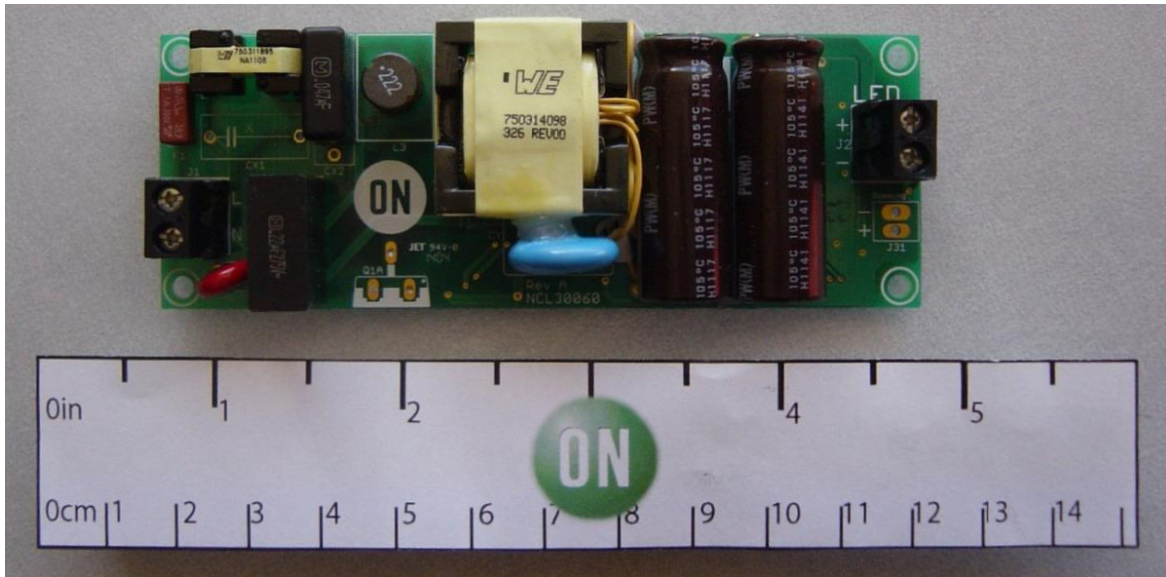


Figure 1. NCL30060G Evaluation Board (Top Side)

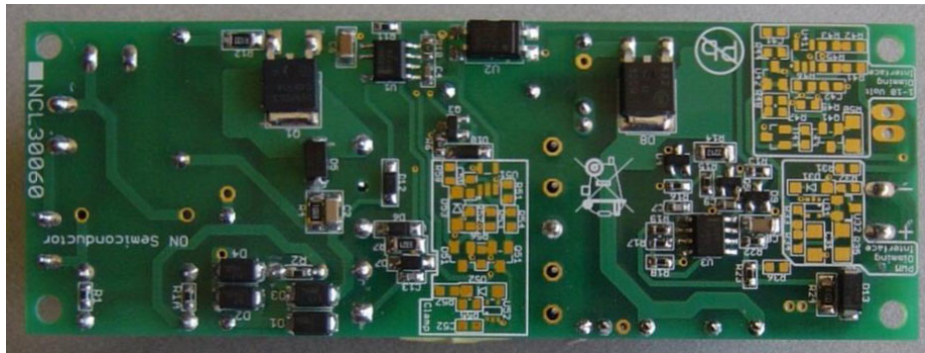


Figure 2. NCL30060G Evaluation Board (Bottom Side)

NCL30060GEVB

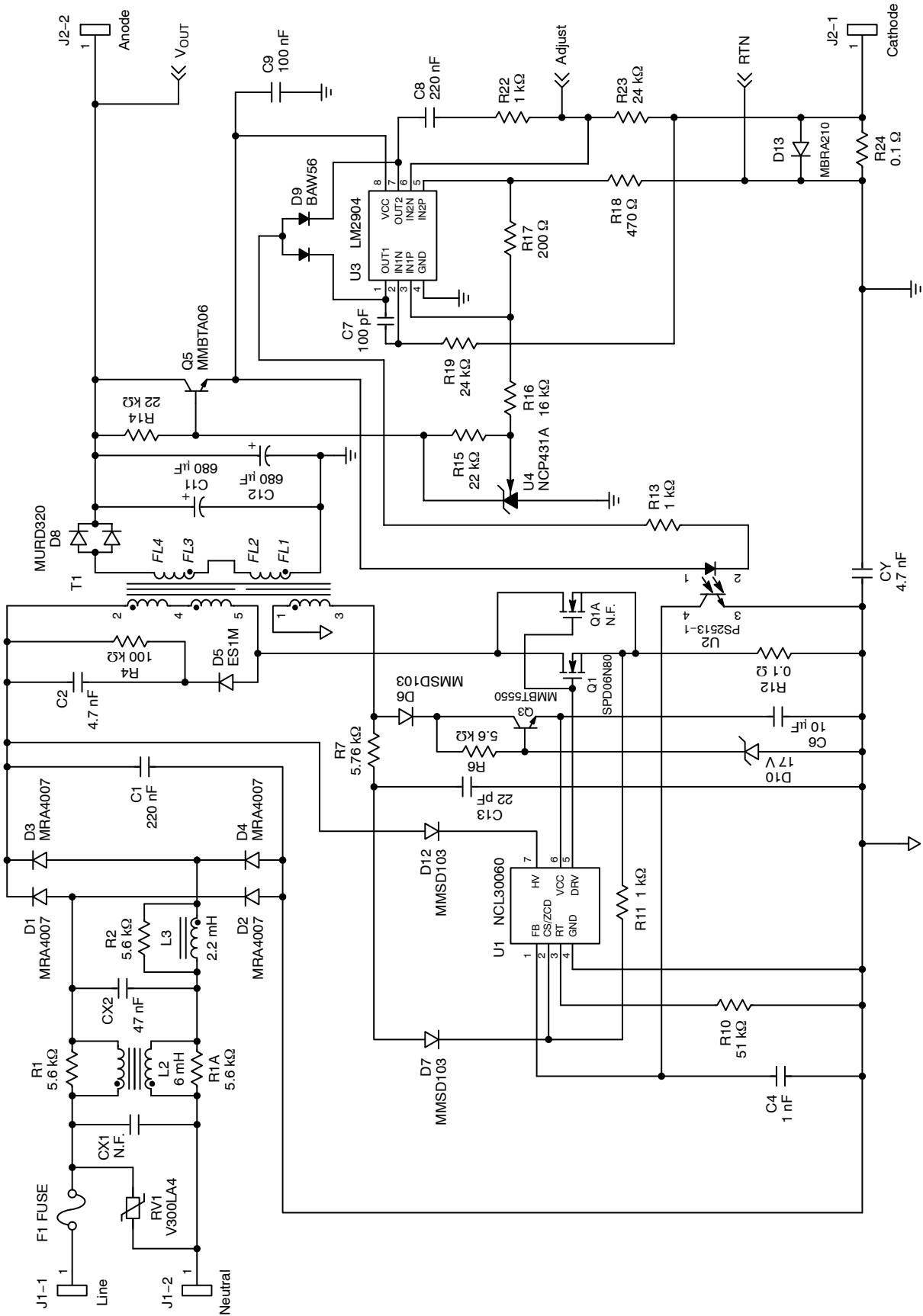


Figure 3. Power Stage Schematic

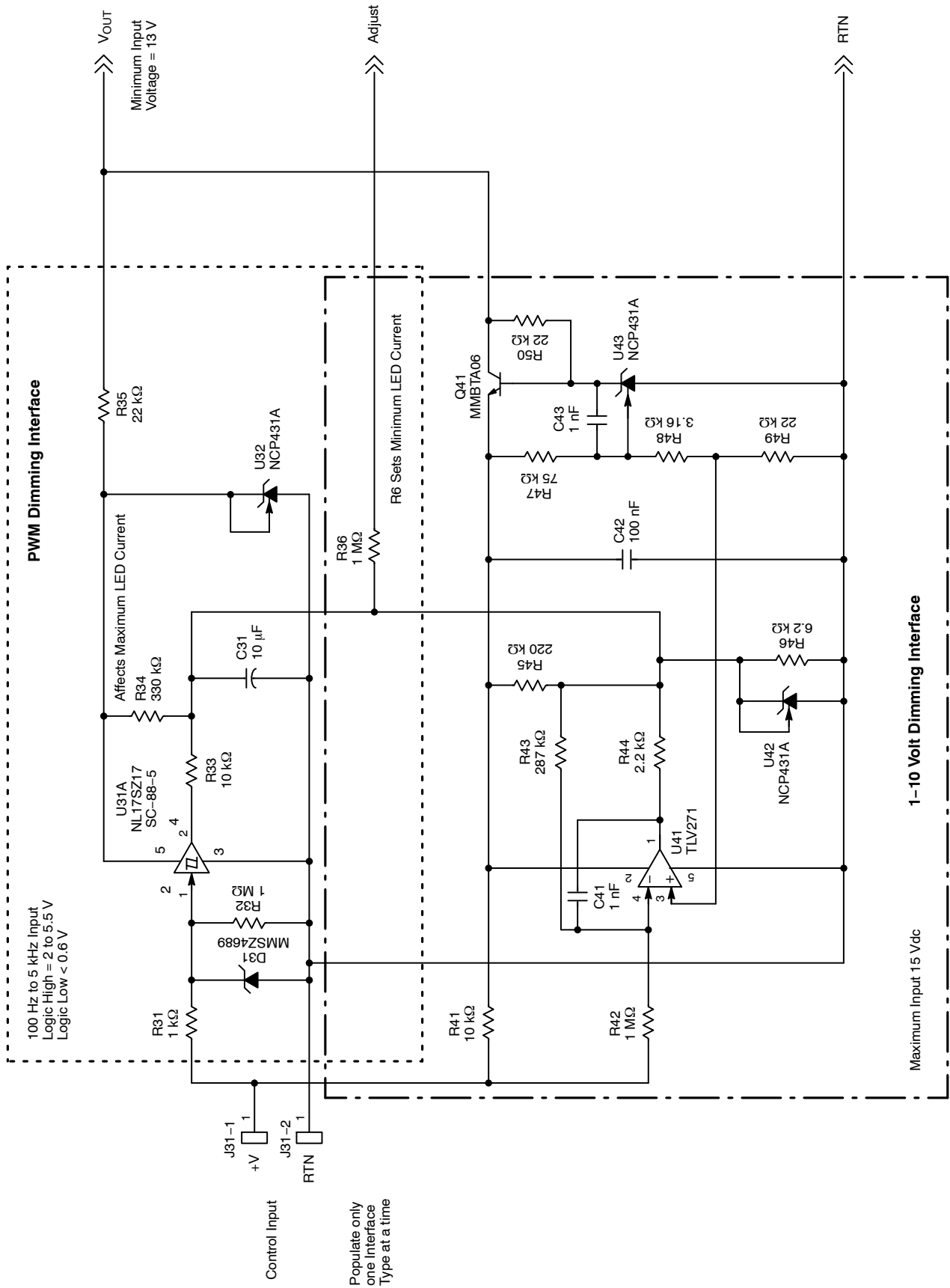


Figure 4. Dimming Control Schematic

General Behavior/Waveforms

The evaluation board is based on a single stage flyback converter. This topology provides isolation and high power factor utilizing a single power magnetic and switching device. Single stage converters require minimizing filter capacitance after the diode bridge and loop response less than 20 Hz to achieve high power factor and low THDi. Shown below are waveforms of Q1 switching MOSFET drain voltage and current as monitored across sense resistor R12. The evaluation board is operating with 25 W LED load. Note the scale factors were left unchanged between photos to highlight the relationship between drain voltage, current, and operating frequency.

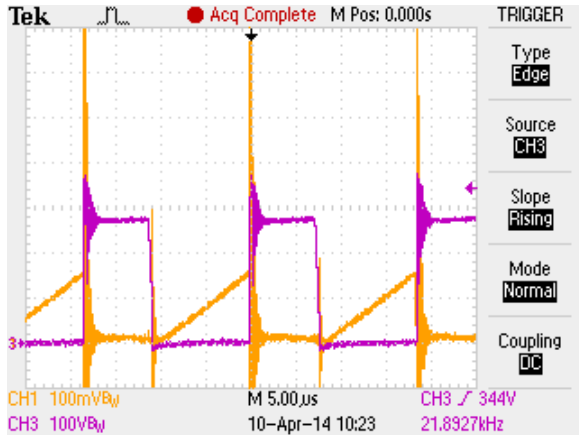


Figure 5. Drain Voltage and Current at 90 V ac Input

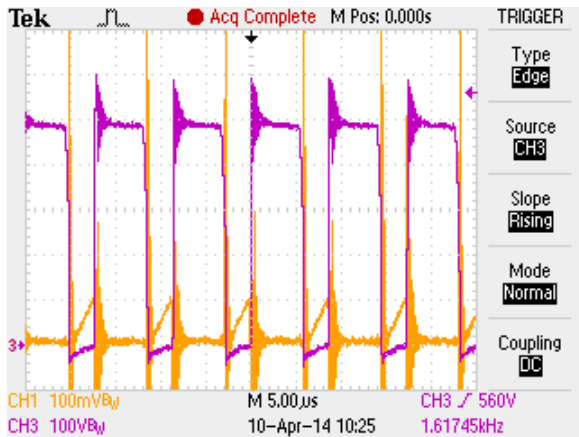


Figure 6. Drain Voltage and Current at 230 V ac Input

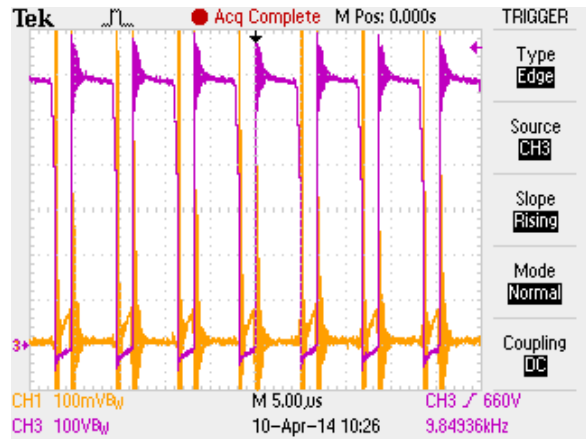


Figure 7. Drain Voltage and Current at 305 V ac Input

The photo below is the drain voltage showing the envelope of the rectified sine wave input. The rectified sine shape provides high power factor performance.

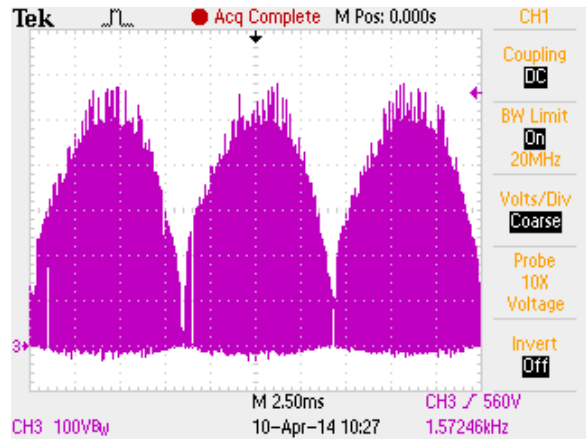


Figure 8. Drain Voltage at 230 V ac with Slower Scan

This converter operates in critical conduction mode (CrM) where the power switch turns on as soon as the transformer core is reset to provide maximum utilization of the transformer. This can be seen in Figure 9 which shows the bias winding voltage in the top trace and the switching MOSFET gate signal in the bottom trace.

NCL30060GEVB

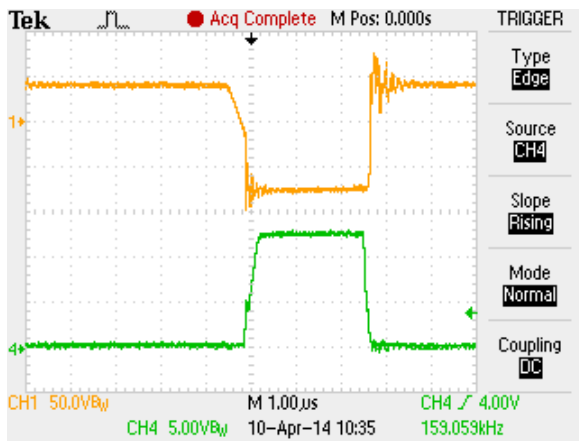


Figure 9. Bias Winding and DRV in CrM Operation

The voltage on the transformer bias winding remains constant until the core is demagnetized, at which time the voltage begins to fall. When the voltage crosses the zero current detect (ZCD) threshold of 55 mV, the gate drive (DRV) is issued which turns on the MOSFET. The DRV signal remains high until the on-time expires and then DRV falls to a low state turning off the MOSFET. When the MOSFET turns off, the bias winding voltage returns to the high state.

Typical Performance

Figure 10 shows efficiency line regulation performance for the evaluation board. Figure 11 is a plot of load regulation with 115 V ac input. Note the converter enters protection modes for very low and very high output voltage.

Power Factor and input current total harmonic distortion (THDi) is shown in Figure 12 for the evaluation board driving 12 LED load. Curves for both 50 Hz and 60 Hz operation are shown.

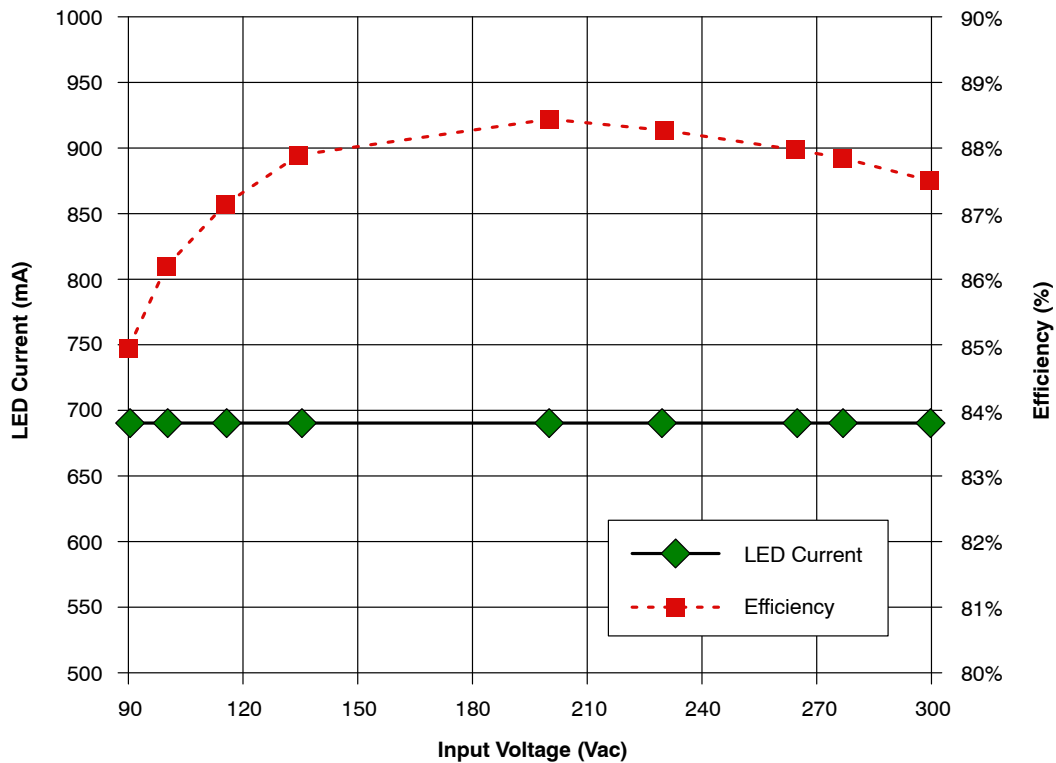


Figure 10. Efficiency and Line Regulation

NCL30060GEVB

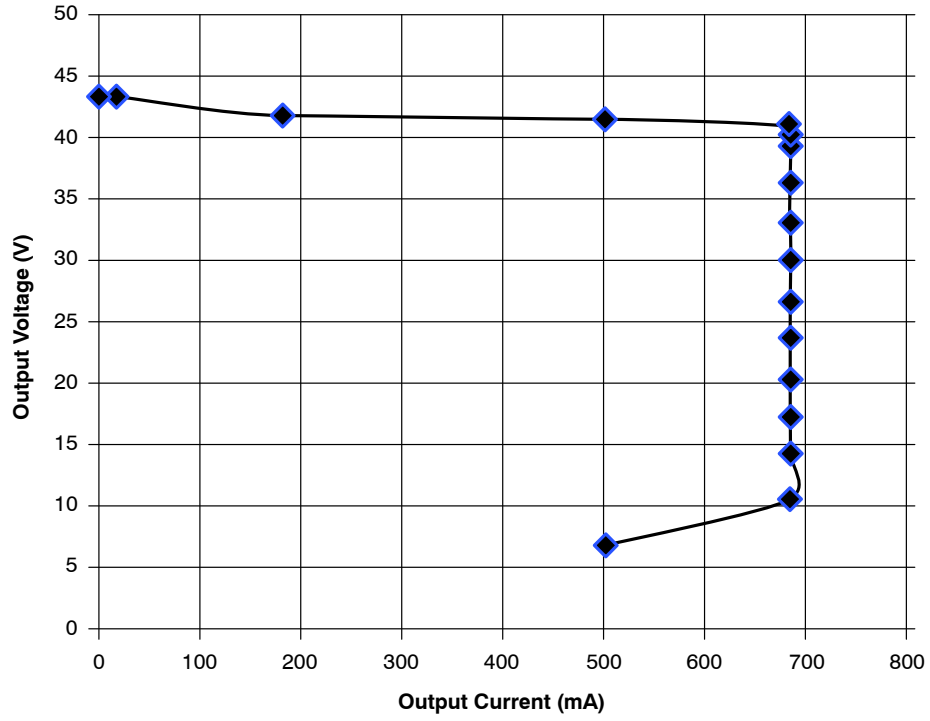


Figure 11. Load Regulation

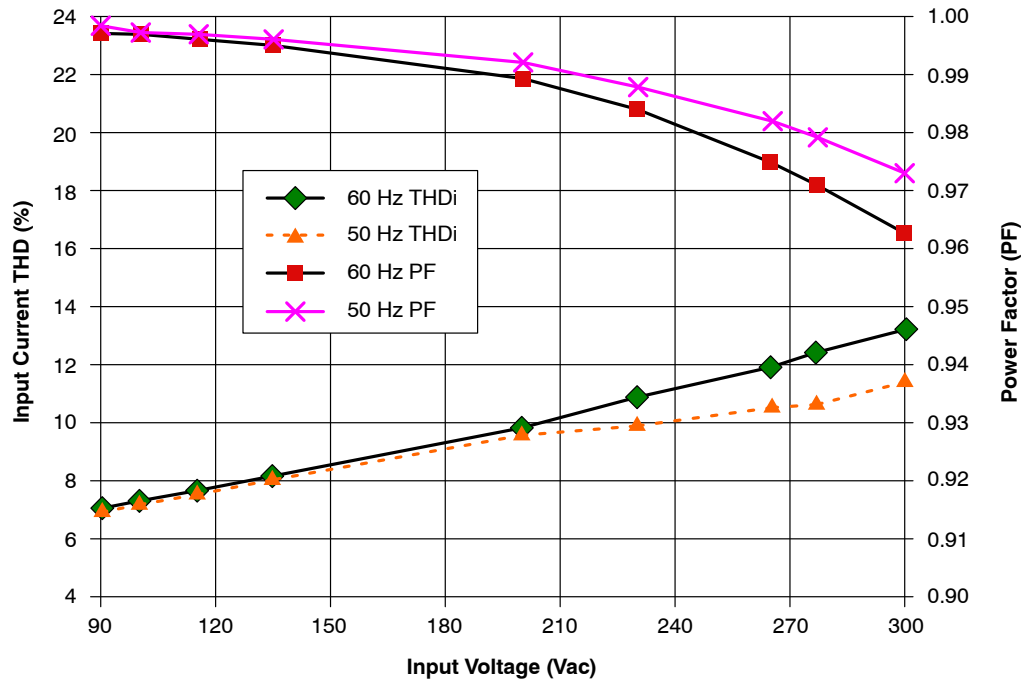


Figure 12. Power Factor and THDi

Setting Output Current

The LED output current is directly sensed to provide good regulation over a wide operating range. Current is sensed via a resistor (R24) placed in series with the negative output lead and the voltage across this resistor is compared to a reference to generate a feedback signal. The feedback signal is passed to the primary to control the on-time of the NCL30060 providing closed loop operation.

The loop response of this single stage converter is low in order to provide high power factor and low THDi. At startup, the output current will overshoot until the control loop has time to respond. The amount of overshoot is controlled by a second feedback loop called the fast loop. This loop activates quickly at startup and limits the output current, but does not provide high power factor performance. After a delay, the main current loop takes over regulation at the target current while maintaining high power factor. The current threshold for the fast loop must be set higher than the peak of the LED ripple current to ensure optimal power factor performance. Resistors R16, R17, and R18 establish the proper reference levels for the main and fast current loops. As built, the reference for the main loop is 70 mV, and the fast loop is 100 mV.

The LED output current, I_{LED} , is given by the formula below:

$$I_{LED} = \frac{70 \text{ mV}}{R24} \quad (\text{eq. 1})$$

The default value for R24 is 0.1 Ω , therefore the LED current will be 700 mA.

I_{LED} can also be set by adjusting the reference dividing resistors R16, R17, and R18. Ensure that the reference level on the fast loop is higher than the peak of the LED ripple current to avoid degrading the power factor.

Adjusting Output Voltage Range

The NCL30060 evaluation board was designed to cover a wide range of customer applications. As delivered, it is configured for 700 mA over a voltage range of 10 to 41 V. Lower voltage/higher current configurations can also be supported with a simple modification.

The transformer secondary winding is comprised of two halves. The evaluation board default configuration is a series connection of the two secondary windings. For LED voltage applications of 9 to 20 V, the secondary windings should be changed to a parallel configuration. LED string voltages below 9 V will require an alternate transformer design which provides proper secondary bias voltage.

The transformer secondary uses four wires (Flying Leads) from the magnetic to the PCB. Table 1 below shows the two possible configurations for secondary windings.

Table 1. TRANSFORMER WIRE CONNECTIONS

Transformer Wire Number	Default PCB Wire Location (Series)	PCB Location for Low Voltage (Parallel)
FL1	H6	H6
FL2	H3	H2
FL3	H4	H5
FL4	H1	H1

Open Load Protection

The evaluation board is configured as a current source; therefore the output voltage will increase until the current set point of 700 mA is achieved. If no load is connected, the output voltage would rise excessively and must be limited to avoid damage to the output capacitors. The NCL30060 ZCD input monitors the output voltage via the bias winding voltage which is related to the output voltage by the turns ratio of the transformer. R7, D7, and R11 form the path from the bias winding to the ZCD input. When the ZCD input reaches 6 V, the controller shuts off the MOSFET preventing excessive output voltage. The recommended value of R11 is 1 k Ω to provide proper response of the current sense function. R7 is selected to provide 6 V on the ZCD input when the LED output voltage reaches the open load protection threshold. C13 is a noise filter for ZCD operation.

Shown in Figure 13 below is the bias winding in the top trace and the main secondary voltage in the lower trace. Note the right side showing a rising voltage when the MOSFET turns off.

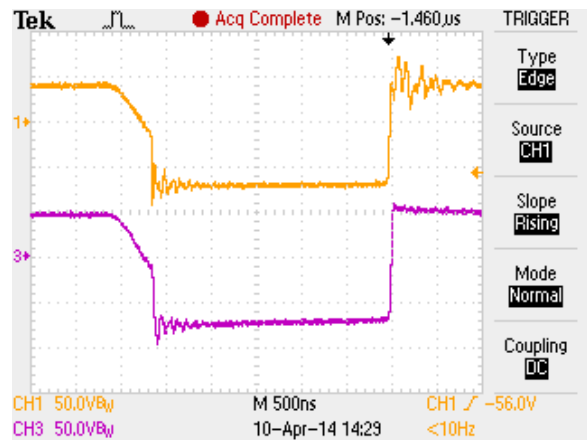


Figure 13. Bias Winding Ringing Compared to Secondary Winding Waveform

The ringing on the bias winding (top trace) compared to the secondary winding (lower trace) reveals an error

introduced by the transformer leakage inductance. Monitoring the bias winding to detect output voltage directly would indicate a false open load condition. The NCL30060 measures the ZCD pin 2 μ s after the MOSFET turns off to allow the ringing to subside and avoid erroneous readings caused by leakage inductance.

When the NCL30060 detects an open load condition, the MOSFET is turned off and is held off for 1.25 ms, at which time another DRV pulse is issued. If the open load condition is still present, the MOSFET will be turned off again for 1.25 ms. Should four events occur in succession, the controller shuts down for 1 second to protect the system, and then attempts a restart. Qualifying four events avoids an interruption in operation due to disturbance such as surge or static discharge.

Figure 14 below is the bias winding voltage in the top trace and the DRV in the lower trace during an open load condition. Note the 1.25 ms periods of no switching and after the fourth consecutive event the controller shuts off for the extended 1 second period.

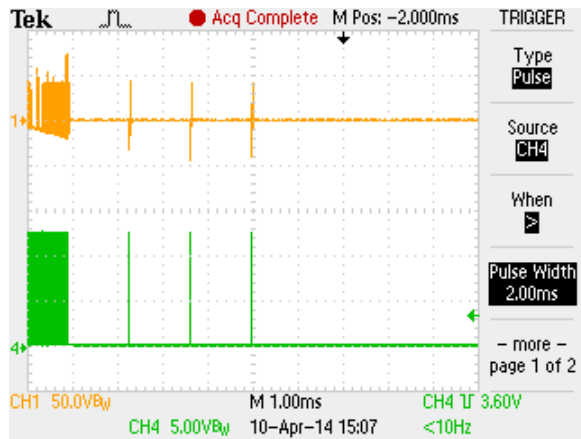


Figure 14. Open Load Protection Shutdown

The CS/ZCD pin monitors primary current during the MOSFET on-time and bias winding voltage during off-time. D7 is a blocking diode which allows this dual sensing. Note that capacitance on the CS/ZCD pin will affect converter operation. Typically, this pin cannot be directly monitored as probe capacitance can alter circuit timing. Additionally, board capacitance and recovery characteristics of D7 can affect converter operation. Best performance is achieved by selecting a low capacitance diode with recovery time of less than 35 ns for D7 to avoid residual voltage on the CS/ZCD pin as the converter naturally progresses from on-time to off-time. PCB traces should be kept as short as possible to avoid parasitic capacitance.

Shorted Output Protection

During the on-time, energy is stored in the flyback transformer and during the off-time the energy is delivered to the secondary. When the converter is operating with low output voltage, the off-time is extended as it is the product of voltage and time which demagnetizes the transformer

initiating the next switching cycle in CrM operation. Normal converter startup produces the same extended off-times as shorted output requiring differentiation between these two events for proper protection.

High power factor operation further compounds detection of shorted output due to the fact the energy transfer follows the rectified sine envelope of the applied power. The extended off-time characteristic of a shorted output may only occur near the peaks of the sine envelope making a standard timer based solution not possible. A novel asymmetrical detection method accounts for the extended off-time occurring only at the peaks of the applied voltage. Further details on shorted output detection can be found in the [NCL30060](#) datasheet.

Shown below is the typical response of the evaluation board to a shorted output. This trace shows output current flowing for about 40 ms before the shorted output detection circuit shuts off the converter. After a 1 second delay, the converter attempts a restart. When the shorted output is removed, recovery is automatic.

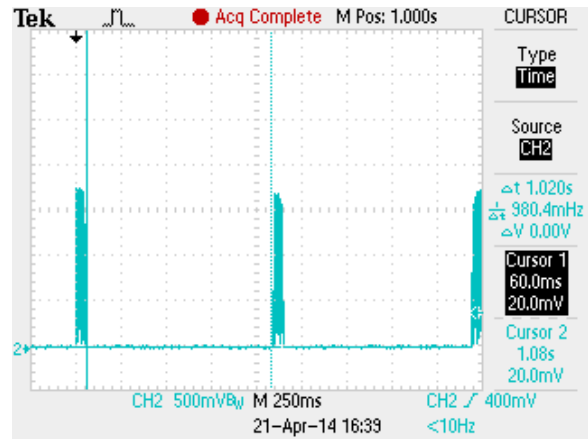


Figure 15. Current Pulses during Shorted Output

Dimming Functions

The NCL30060 evaluation board accepts dimming control functions through screw terminal connector J31. The board is factory configured for 1–10 V control, but can be easily modified for PWM dimming control by installing alternate components on the PCB. The dimming interface is referenced to the secondary ground, but does not share the negative lead of the LED load. **Do not make a connection between the negative of J31 and the negative of output connector J2. This will interfere with LED current sensing.**

1–10 Volt Dimming

The typical 1–10 V dimming control for lighting provides full output when the dimming control is at 10 V and minimum output at 1 V or below. The interface on the NCL30060 evaluation board will accept a direct connection to a voltage source, such as a variable dc supply to achieve dimming over the 1 to 10 volt range. Multiple LED driver

boards can be connected in parallel allowing control of many lighting fixtures from one variable dc supply.

The dimming interface will also support dimming control using a potentiometer noting that the evaluation board interface is capable of sourcing 10 V. (Note, a logarithmic taper potentiometer is suggested for more proportional light control with potentiometer setting.) Multiple fixtures can be connected together when using a potentiometer; however the adjustment region will be more compressed. This is due to multiple LED drivers where each dimming interface is contributing some current to the same potentiometer.

An alternate approach to a potentiometer is a commercial 1–10 V dimming control. An example of this control is a potentiometer which has a transistor follower as a current buffer to minimize the effect of current sourced from multiple dimming interface circuits. The 1–10 volt dimming interface will work with all three control methods.

The 1–10 volt dimming control injects a proportional signal into the current feedback loop essentially subtracting the control input proportionally from the feedback required from the LED current sense resistor. This provides a stable wide-range dimming control. 10 volts on the input provides zero output from the summing amplifier U41. R45 in conjunction with R44 and R46 results in zero current through R36 which means no modification to the current feedback. Therefore, full LED is applied to the load. A voltage higher than 10 V has no effect on the feedback loop. Maximum voltage at the dimming control input is 15 V.

As the dimming control voltage is reduced, U41 amplifies the signal and raises the voltage on R36, which proportionally reduces the feedback signal from the sense resistor. U42 clamps this summed signal to 2.5 V when the dimming input is lowered to 1 V. Further reduction in dimming input voltage will have no effect due to the clamping of U42. The value of R36 determines the minimum current flowing through the LED load. The formula to calculate R36 is given below:

$$R_{36} = \frac{R_{23} \times (V_{U42} - K)}{K - I_{LED} \times R_{24}} \quad (\text{eq. 2})$$

Where:

$$K = V_{U4} \times \left(\frac{R_{18}}{R_{16} + R_{17} + R_{18}} \right) \quad (\text{eq. 3})$$

For the example evaluation board with minimum LED current of 120 mA, R36 is approximately 1 MΩ.

PWM Dimming

Components to support a PWM dimming input can be placed on the NCL30060 evaluation board in the designated area. Components used for 1–10 V dimming must be removed when using the PWM dimming input. The evaluation board converts the PWM signal to an analog level. Therefore the LED current responds to the average duty factor of the PWM signal being subtracted from the full LED current. For example, a PWM signal which is at the high state for 10% will result in 90% of the full LED current. A PWM signal which is at the high state 70% of the time will result in an LED current of 30% of maximum.

U31 is a Schmitt trigger buffer which receives the PWM signal providing a fixed amplitude square wave with fast rise and fall times. R33 and C31 filter the PWM signal to an average level which is then impressed on R36. Since the PWM input is converted to an analog voltage to linearly dim the LED current, the PWM frequency is not critical. PWM frequencies from 100 Hz up to 20 kHz are acceptable. The control method functions the same as with the 1–10 V dimming.

R31 and D31 limit the PWM dimming signal to 5.1 V protecting the input of U31. 12 V is the maximum input. R2 ensures if no PWM signal is applied, the LED current will be at the maximum level. R34 sets the maximum level when duty factor is 0%. If R34 is omitted, the maximum LED current will be slightly higher than the target value without the PWM dimming circuit.

“Clamp”

There is an area on the bottom side of the PCB labeled “Clamp”. These component locations are reserved for a future enhancement. The demo board is shipped without populating this area.

NCL30060GEVB

Table 2. BILL OF MATERIALS

Designator	Qty.	Description	Value	Tolerance	Footprint	Manufacturer	Manufacturer Part Number	Substitution Allowed
CY	1	Capacitor, Y5U X1Y1	4.7 nF, 250 VAC	20%	Radial	Panasonic	CD16-E2GA472MYNS	Yes
CX1	0	DNP	-	-	Box	-	-	-
CX2	1	Metallized Polyester Film X1	47 nF, 300 VAC	20%	Box	Panasonic	ECQ-U3A473MG	Yes
C2	1	Ceramic	4700 pf, 500 V	10%	1206	TDK	CGJ5H4X7R2H472K115AA	Yes
C1	1	Metallized Polyester Film X1	220 nF, 300 VAC	20%	Box	Panasonic	ECQ-U2A224ML	Yes
C4	1	Ceramic COG	1 nF, 50 V	10%	0603	TDK	C1608COG1H102K080AA	Yes
C7	1	Ceramic COG	100 pF, 50 V	5%	0603	TDK	C1608COG1H101J080AA	Yes
C6	1	Ceramic	10 μ F, 35 V	15%	1206	TDK	C3216X7R1V106M	Yes
C8	1	Ceramic X7R	220 nF, 50 V	10%	1206	TDK	C3216X7R1H224K115AA	Yes
C9	1	Ceramic X7R	100 nF, 50 V	10%	0603	TDK	C1608X7R1H104K080AA	Yes
C11, C12	2	Aluminum Electrolytic	680 μ F, 63 V	20%	Radial	Nichicon	UPW1J681MHD6	Yes
C13	1	Ceramic NPO	22 pF, 50 V	5%	0603	TDK	C11608C0G1H220J080AA	Yes
D1, D2, D3, D4	4	Rectifier	1000 V, 1 A	-	SMA	ON Semiconductor	MRA4007T3	No
D5	1	Fast Rectifier	1 A 1000 V	-	SMA	Micro Commercial	ES1M	Yes
D6, D7	2	Diode	250 V, 200 mA	-	SOD123	ON Semiconductor	MMSD103T1G	No
D8	1	RECTIFIER	200 V, 3 A	-	DPAK	ON Semiconductor	MURD320T4G	No
D9	1	Diode	70 V, 200 mA	-	SOT23	ON Semiconductor	BAW56LT1G	No
D10	1	ZENER, Low Current	17 V	5%	SOD123	ON Semiconductor	MMSZ4704T1G	No
D12	1	Diode	250 V, 200 mA	-	SOD123	ON Semiconductor	MMSD103T1G	No
D13	1	Schottky Rectifier	10 V, 2 A	-	SMA	ON Semiconductor	MBRA210LT3G	No
F1	1	Slow Blow TE5 Series	1 A	-	Axial	Littelfuse	36911000440	Yes
J1, J2	2	2 Position Terminal Block	-	-	Through Hole	Wiedmuller	1716020000	Yes
L2	1	Dual Coil	6 mH, 1.6 Ω , 500 mA	10%	Through Hole	Würth Midcom	750311895	Yes
L3	1	Drum Inductor	2.2 mH	10%	Through Hole	Würth Midcom	768772222	Yes
Q1	1	N-Channel MOSFET	800 V 6 A 0.9 Ω	-	DPAK	Infineon	SPD06N80C3	Yes
Q1A	1	DNP	-	-	TO-220	-	-	-
Q3	1	NPN Transistor	140 V, 600 mA	-	SOT23	ON Semiconductor	MMBT5550LT1G	No
Q5	1	NPN Driver Transistor	80 V, 500 mA	-	SOT23	ON Semiconductor	MMBTA06LT1G	No
RV1	1	Varistor	300 V, 25 J	-	Radial	Littelfuse	V300LA4P	Yes
R1, R1A, R2, R6	4	Resistor	5.6 k Ω , 1/10 W	5%	0603	Panasonic	ERJ-3GEYJ562V	Yes
R4	1	Resistor	100 k Ω , 1/4 W	5%	1206	Various	Various	Yes
R7	1	Resistor	5.76 k Ω , 1/4 W	1%	1206	Various	Various	Yes
R10	1	Resistor	51 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R11	1	Resistor	1 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R12	1	Resistor	0.1 Ω , 1/4 W	1%	1206	Rohm Semi	MCR18EZHFLR100	Yes
R13	1	Resistor	1 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R14	1	Resistor	22 k Ω , 1/4 W	5%	1206	Various	Various	Yes
R15	1	Resistor	22 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R16	1	Resistor	16 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R17	1	Resistor	200 Ω , 1/10 W	1%	0603	Various	Various	Yes
R18	1	Resistor	470 Ω , 1/10 W	1%	0603	Various	Various	Yes
R19, R23	2	Resistor	24 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R22	1	Resistor	1 k Ω , 1/10 W	1%	0603	Various	Various	Yes
R24	1	Resistor	0.1 Ω , 1/4 W	1%	1206	Rohm Semi	MCR18EZHFLR100	Yes
R36	1	Resistor	1 M Ω , 1/10 W	1%	0603	Various	Various	Yes
T1	1	Transformer, 25 W	XFMR	-	EFD25	Würth Midcom	750314098 Rev01	Yes

NCL30060GEVB

Table 2. BILL OF MATERIALS (continued)

Designator	Qty.	Description	Value	Tolerance	Footprint	Manufacturer	Manufacturer Part Number	Substitution Allowed
U1	1	Single Stage PFC LED Driver	NCL30060	-	SOIC7	ON Semiconductor	NCL30060	No
U2	1	Opto Coupler	80 V, 50 mA	-	SMT4	NEC Electronics	PS2513L-1-A	Yes
U3	1	Dual Op Amp	LM2904	-	SOIC8	ON Semiconductor	LM2904DR2G	No
U4	1	Programmable Reference	NCP431AVSN	1%	SOT23	ON Semiconductor	NCP431AVSNT1G	No

1-10 V DIMMING INTERFACE

C41, C43	2	Ceramic COG	1 nF, 50 V	10%	0603	TDK	C1608COG1H102K080AA	Yes
C42	1	Ceramic X7R	100 nF, 50 V	10%	0603	TDK	C1608X7R1H104K080AA	Yes
J31	1	2 Pin Connector	2.54MM Pitch	-	Through Hole	On Shore Technology	OSTVN02A150	Yes
Q41	1	NPN Driver Transistor	80 V, 500 mA	-	SOT23	ON Semiconductor	MMBTA06LT1G	No
R41	1	Resistor	10 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R42	1	Resistor	1 MΩ, 1/10 W	1%	0603	Various	Various	Yes
R43	1	Resistor	287 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R44	1	Resistor	2.2 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R45	1	Resistor	220 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R46	1	Resistor	6.2 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R47	1	Resistor	75 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R48	1	Resistor	3.16 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R49	1	Resistor	22 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R50	1	Resistor	22 kΩ, 1/4 W	5%	1206	Various	Various	Yes
U41	1	op amp	TLV271	-	TSOP-5	ON Semiconductor	TLV271SN1T1G	No
U42, U43	2	Programmable Reference	NCP431AVSN	1%	SOT23	ON Semiconductor	NCP431AVSNT1G	No

OPTIONAL PWM DIMMING INTERFACE (DNP)

C31	0	Ceramic X7S, DNP	10 μF, 6.3 V	20%	0603	TDK	C1608X7S0J106M080AC	Yes
D31	0	ZENER, low current, DNP	5.1 V	5%	SOD123	ON Semiconductor	MMSZ4689T1G	No
R31	0	Resistor, DNP	1 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R32	0	Resistor, DNP	1 MΩ, 1/10 W	1%	0603	Various	Various	Yes
R33	0	Resistor, DNP	10 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R34	0	Resistor, DNP	330 kΩ, 1/10 W	1%	0603	Various	Various	Yes
R35	0	Resistor, DNP	22 kΩ, 1/4 W	5%	1206	Various	Various	Yes
U31	0	Schmitt Buffer, DNP	NL17SZ17	-	SC-88A	ON Semiconductor	NL17SZ17DFT2G	No
U32	0	Programmable Reference, DNP	NCP431AVSN	1%	SOT23	ON Semiconductor	NCP431AVSNT1G	No

NOTE: All devices are Pb-Free

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